General Examination: Numerical Analysis and Ordinary Differential Equations

Problem 1. Define the IEEE Standard 754 Floating Point representation of a finite precision number stored in a computer for

- (a) single precision representation
- (b) double precision representation
- (c) Let x be the real number x = 4/3. Define \tilde{x} as the IEEE Standard 754 Floating Point single precision machine representation of x using rounding to the nearest. Determine \tilde{x} .
- (d) Using the machine representation \tilde{x} of x found in (c), evaluate the expression $z = 1 3(\tilde{x} 1)$. Explain any issues or anomalies with this computation.

Problem 2. (A hand calculator is required.) Find ALL of the real zeros of the function $g(x) = 2x - (1 + x^2) \tan^{-1} x$. Find the positive zeros with 4 decimal place accuracies. Verify the accuracies.

Problem 3.

- (a) Let A be a real $m \times n$ matrix and let ||X|| denote the Euclidean norm on \mathbb{R}^n . Define the associated induced matrix norm ||A||.
- (b) Let $A = \begin{pmatrix} 1 & 2 \\ 0 & 2 \end{pmatrix}$. Use the definition above to show that to 4 decimal digits $||A|| \approx 2.9208 > \sqrt{8}$.

Problem 4. Given an $m \times n$ real matrix A, an n-dimensional real column vector X and an m-dimensional real column vector B, the matrix equation AX = B represents a system of m linear equations in n unknowns.

- (a) In case m = n and A is non-singular, provide a detailed description of an algorithm for computing the solution X using the decomposition PA = LU, where P, L, and U are $n \times n$ matrices, P a permutation matrix, L lower triangular with 1's on the main diagonal and U upper triangular.
- (b) How are the entries of L determined?
- (c) Under what sets of conditions can the permutation matrix P be taken as the $n \times n$ identity I_n ?

- (d) Suppose A is $m \times n$ with m > n. Discuss a method for determination of vectors X that minimize $||AX B||^2$ (i.e. the "least squares" solutions), where $|| \cdot ||$ denotes the Euclidean norm. Under what condition does a *unique solution* exist?
- (e) In part (d) suppose that A has a large condition number $\kappa(A)$. Describe a numerically reliable technique for determining the unique least squares solution.

Problem 5. Given the equation $\frac{dx}{dt} = x \sin x$,

- (a) Find all fixed points.
- (b) Plot its vector field.
- (c) Classify all the fixed points.
- (d) Plot the solutions in the *tx*-plane satisfying the initial conditions $x(0) = \pi/4$, $x(0) = \pi$, $x(0) = 8\pi/7$ and $x(0) = -\pi/6$.

Problem 6. For the differential equation $\frac{dy}{dt} = y(2y^2 - y^4 + \alpha)$, where α is a parameter,

- (a) Find all bifurcation values of α as α varies on the real line $-\infty < \alpha < \infty$.
- (b) Classify the bifurcations obtained in (a).
- (c) Plot the bifurcation diagram that also displays the stability of fixed points.

Problem 7. (a) Suppose that the system

$$\frac{dx}{dt} = f(x, y),$$
$$\frac{dy}{dt} = g(x, y)$$

is conserved with the conserved quantity E(x, y). Show that the system has neither spirals, nor stable and unstable fixed points. As a consequence, show that if its linearized system about a fixed point (x_0, y_0) has a center, then (x_0, y_0) is a center as well.

(b) Show that a Hamiltonian system

$$\frac{dx}{dt} = \frac{\partial H}{\partial y},$$
$$\frac{dy}{dt} = -\frac{\partial H}{\partial x}$$

is conserved.

Problem 8. For the system

$$\frac{dx}{dt} = x(2 - x - y),$$
$$\frac{dy}{dt} = y(y - x^2),$$

- (a) find fixed points, and use linear analysis to classify them if the analysis applies;
- (b) in the phase plane, plot nullclines, and plot the vector field on the nullclines;
- (c) sketch the phase portrait using the results of (a) and (b).

Problem 9. (Bonus problem) Suppose that N = N(t) is the population density of a species, satisfying the differential equation

$$\frac{dN}{dt} = \alpha - \beta N - \gamma e^{-\delta N},$$

where α , β , γ and δ are positive parameters.

(a) Use dimension analysis to rewrite the equation in the dimensionless form

$$\frac{dx}{d\tau} = a - bx - e^{-x}$$

with the dimensionless parameters a > 0 and b > 0.

- (b) Show that the system in (a) could have no fixed point, one, or two fixed points, depending on the values of a and b. Then classify the fixed points.
- (c) Show that bifurcations occur at a = 1 and $a = b b \ln b$. Then classify the bifurcations.
- (d) Plot a stability diagram in the *ab*-plane and identify the regions in the first quadrant where the system has no, one, or two fixed points.