

Resource-Bounded Intruders in Denial of Service Attacks

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CSF 2019 – Hoboken, NJ
June 25-28, 2019

Denial of Service attacks are a serious security concern:

- ▶ No service is protected against DoS attacks:
flooding attacks can be performed by attackers with large amounts of resources;
- ▶ Some DoS attacks do not require large amounts of resources:
asymmetric DoS attacks,
amplification attacks,
slow DoS attacks including **SlowDroid attacks** where a web server can be taken down by a single mobile phone

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Intruders also exploit various **types of resources**:

- ▶ limited number of **workers** web-servers possess (Slowloris);
- ▶ limited amount of TCAM **memory** of switches (SDN TCAM exhaustion attacks);
- ▶ server's **processing power** (TLS renegotiation DoS attacks);
- ▶ network **bandwidth** (SIP forking amplification attacks on VoIP);
- ▶ ...

Resource-Bounded Intruders

- **Dolev-Yao intruder** with **unlimited resources** can trivially render any service unavailable.
- It is useful in practice and more challenging for formal verification to determine whether a service is vulnerable to intruders with **limited resources**, *i.e.*, **Resource-Bounded Intruders**,

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 - ▶ **Bounded Traffic Intruder Model** - intruder can send only a number of messages at a given rate, *e.g.*, messages per second.
 - ▶ **Bounded Processing Intruder Model** - according to his processing power, intruder can carry out only a bounded number of actions in a given time window.
 - ▶ **Bounded Memory Intruder Models** - intruder uses only a bounded amount of memory.

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 - ▶ similar to the standard Dolev-Yao intruder
 - able to create fresh values, compose messages, encrypt and decrypt messages with available keys, etc.;
 - ▶ amended with resource and time features
 - an intruder can only consume at most some specified amount of resources in any given time window.

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- ▶ We obtain complexity results for the related verification problems.
- ▶ We automate the search for DoS attacks using Maude.

Model: Multiset Rewriting with Real Time

Timestamped Fact - An atomic FOL formula F with an associated **real** number t , $F@t$. $Time@t$ specifies the global time.

Configuration - A multiset of facts with exactly one occurrence of the fact $Time$.

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Timestamps of facts may denote:

▶ **creation/availability:**

$N_S(A, C, m)@t$ denotes that message m was sent by agent A
on transmission medium C **at moment t** ;

$E@t$ denotes empty memory slot available **from the moment t** ;

▶ **validity/expiration:**

$T_i@t$ denotes that the protocol state S_i **times out at moment t** .

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Formalizing **time requirements**:

- Configurations may have time constraints attached:

$$\text{e.g., } Time@T, \tau_i^{A_k}(S, \vec{X})@T_1 \mid T_1 \geq T + 1$$

denoting that protocol state S_i will time out in 1 time unit.

Time Constraints - comparisons of time variables:

$$T > T' \pm D \quad \text{and} \quad T = T' \pm D$$

where T and T' are time variables, and D is a natural number.

Model: Multiset Rewriting with Real Time

Formalization involves **explicit real time** and **time requirements**, *i.e.*, comparisons of time variables.

Tick Rule - Advances global time by any positive **real** number ε :

$$Time@T \longrightarrow Time@(T + \varepsilon)$$

Instantaneous Rule - Changes the state, but not the global time:

Time Constraints:

$$T > T' \pm D \text{ and } T = T' \pm D$$

$$Time@T, \mathcal{W}, F_1@T'_1, \dots, F_n@T'_n \mid C \longrightarrow \exists \vec{x}. Time@T, \mathcal{W}, Q_1@(T + D_1), \dots, Q_m@(T + D_m)$$

where D_1, \dots, D_m, D are natural numbers and \vec{x} are nonces.

Execution time of actions - rules may have explicit **duration**, specified by timestamps of created facts.

Formalization also involves **resource** management and requirements.

Services allocate their available resources to each client request for some period of time.

- ▶ Resources are **consumed** and **recovered** during **protocol execution**:

$$\begin{aligned} & \text{Time}@T, S_i(S, S_{id}, r_i, \vec{X}_i)@T_1, \mathbf{R}(S, R + r_j - r_i + r_{min}^S)@T_2, \\ & \quad \mathbf{N}(m_i)@T_3, \mathcal{W}_1, \mathcal{W} \mid T_1 \geq T, T_2 \leq T, T_3 \leq T \longrightarrow \\ & \text{Time}@T, S_j(S, S_{id}, r_j, \vec{x}_j)@(T + t_j), \mathbf{R}(S, R + r_{min}^S)@T, \mathcal{W}_2, \mathcal{W} \end{aligned}$$

Special facts, variables and constants are used in the model:

$\mathbf{R}(s, r)@t$ - service s has r **resources available** at moment t ;

r_{min}^S **minimal service resource** - the lower bound on resources required by the service S to work;

r_{ini}^S **initial service resources** for the service S .

Formalization also involves **resource** management and requirements.

▶ **Service availability rules** specify:

- service is **denied** when resources reach the minimum:

$$\begin{aligned} \text{Time}@T, R(S, r_{min}^S)@T, \text{Av}(S)@T_2 &\longrightarrow \\ \text{Time}@T, R(S, r_{min}^S)@T, \text{Den}(S)@T & \end{aligned}$$

- service is **available** if the resources are greater than the minimum:

$$\begin{aligned} \text{Time}@T, R(S, r_{min}^S + R + 1)@T, \text{Den}(S)@T_2 &\longrightarrow \\ \text{Time}@T, R(S, r_{min}^S + R + 1)@T, \text{Av}(S)@T & \end{aligned}$$

$\text{Av}(s)@t$ - **service s is available** from moment t ;

$\text{Den}(s)@t$ - **service s is unavailable** from moment t .

Denial of Service Attacks

Very short service interruptions may be tolerated in practice.

Hence, the notion of a DoS attack is refined by a duration parameter:

A **DoS attack** on a service is successful if the service's resources are exhausted for some **duration**, $mdur$.

$Time@T, Den(S)@T_1 \mid T \geq T_1 + mdurs$

For simplicity we model only one resource and use natural numbers to represent resources.

Verification: We look for traces representing DoS attacks!

Formalization of the verification scenario:

- ▶ Protocol resource theories - representing used services \mathcal{A}_i
- ▶ natural numbers $mdur_i$, specifying the minimal duration that the resources of the service \mathcal{A}_i have to be consumed to represent a successful DoS attack on that service;
- ▶ Intruder theories \mathcal{I}_j

Resource-Bounded Intruders

- **Dolev-Yao intruder** with unlimited resources - not suitable for DoS verification, leads to many false positives.
- **Resource-Bounded Intruders** - more refined intruder model, -amended with resource and time features:
 - ▶ Intruder has a bounded total amount of resources:
 r_{max}^{id} **total amount of resources** of an intruder id ;
 - ▶ Intruder can only consume a bounded amount of resources in any given time window;
 - ▶ Intruder obeys physical laws related to **time**:
 - obeys network transmission time restrictions;
 - intruder's actions take time to be performed.

Resource-Bounded Intruder Theory

- ▶ Actions of **Resource-Bounded Intruders** have the attached cost, e.g., sending a message to the network:

$$\mathbf{SND:} \quad Time@T, M(I, X)@T_1, R(I, Z + r_R)@T_2 \mid T \geq T_1 \longrightarrow \\ Time@T, N(X)@(T + \delta_L), R(I, Z)@T, Rec(I, r_R)@(T + \delta_R)$$

- sending message X takes intruder I δ_L time units;
- it consumes r_R resources;
- these resources can only be recovered after δ_R time units.

$R(id, r)@t$ - intruder id has r **resources available** at moment t ;

$Rec(id, r)@t$ - intruder id can **recover** r **resources** at moment t .

Verification: We look for traces representing DoS attacks!

A **trace** of MSR rules \mathcal{T} is a sequence of configurations

$$\mathcal{S}_0 \longrightarrow_{r_1} \mathcal{S}_1 \longrightarrow_{r_2} \cdots \longrightarrow_{r_n} \mathcal{S}_n,$$

such that for all i , \mathcal{S}_{i+1} is obtained by applying $r_{i+1} \in \mathcal{T}$ to \mathcal{S}_i .

We are interested in traces that reach some goal.

Goal is a set $\mathcal{GS} = \{ \langle \mathcal{S}_1, \mathcal{C}_1 \rangle, \dots, \langle \mathcal{S}_n, \mathcal{C}_n \rangle \}$ where each \mathcal{C}_j is a set of time constraints and \mathcal{S}_j is a multiset of timestamped facts.

A configuration \mathcal{S} is a **goal configuration** if for some i there is a grounding substitution, σ , such that $\mathcal{S}_i\sigma \subseteq \mathcal{S}$ and $\mathcal{C}_i\sigma$ is true.

Model: Multiset Rewriting with Real Time

We consider traces that do not contain critical configurations, *i.e.*, **non-critical traces**.

Critical Configuration Specification is a set $\mathcal{CS} = \{ \langle \mathcal{S}_1, \mathcal{C}_1 \rangle, \dots, \langle \mathcal{S}_n, \mathcal{C}_n \rangle \}$ where each \mathcal{C}_j is a set of time constraints and \mathcal{S}_j is a multiset of timestamped facts.

A configuration \mathcal{S} is a **critical configuration** if for some i there is a grounding substitution, σ , such that $\mathcal{S}_i\sigma \subseteq \mathcal{S}$ and $\mathcal{C}_i\sigma$ is true.

Non-Critical Reachability Problem:

Given a goal \mathcal{GS} , a critical configuration specification \mathcal{CS} and an initial configuration \mathcal{S}_0 , is there a **non-critical trace** \mathcal{P} of MSR rules \mathcal{T} that leads from \mathcal{S}_0 to a goal configuration?

Complexity Results

Non-Critical Reachability Problem in MSR systems is **undecidable** in general, but is **decidable** for systems containing only balanced rules, assuming an upper-bound on the size of facts, *i.e.*, on the total number of symbols in each fact.

MSR		Non-Critical Reachability
Balanced	untimed	PSPACE-complete
	discrete time	PSPACE-complete
	dense time	PSPACE-complete [new]
Not necessarily balanced		Undecidable

A rule is **balanced** if the number of facts appearing in its pre-condition and its post-condition is the same.

Several challenges in **timed MSR with dense time**, particularly related to the notion of **non-critical traces**:

- ▶ Showing that a trace of a dense time MSR is non-critical involves not only the configurations it contains, but also an **infinite number of configurations** obtained by decomposing *Tick* rules, in order to faithfully capture the continuity of time.
- ▶ Technical results involve abstractions, **circle-configurations**, and the auxiliary notion of **immediate successor configurations**, related to satisfiability of relevant time constraints.

Verification Problems

Protocol Verification: We look for traces representing DoS attacks!

DoS Problem:

Given a verification scenario, can resource-bounded intruders deny some service s_i for the duration $mdur_i$?

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DoS problem is an instance of the **non-critical reachability problem**!

Theorem (DoS problem)

*The DoS problem is **undecidable** in general.*

Theorem (Balanced DoS problem)

*Assuming a bound on the size of facts, the DoS problem for balanced verification scenarios is **PSPACE-complete**.*

Protocol Verification: We look for traces representing DoS attacks!

DoS Problem:

Given a verification scenario, can resource-bounded intruders deny some service s_i for the duration $mdur_i$?

DoS problem is an instance of the **non-critical reachability problem**!

- ▶ initial configuration specifies available resources of each service and each intruder, initial knowledge etc.
- ▶ goal: $Time@T, Den(S)@T_1 \mid T \geq T_1 + mdur_S$
- ▶ critical configurations related to services

Protocol Critical Configuration Specification ensures protocol execution respects timeouts and resource bounds:

- ▶ **Timeout CS:** $\langle \{ \text{Time}@T, S_i(s, S_{id}, R_i, \vec{x}_i)@T_1 \}, \{ T_1 < T \} \rangle$
configurations denoting protocol sessions for which the timeout has passed are critical;

Protocols states may have **timeouts**:

- $S_i(s, S_{id}, r_i, \vec{x}_i)@t$ - protocol state S_i times out at moment t
- once a timeout is reached, protocol session ends.

$$\text{Time}@T, R(s, R)@T_1, S_i(s, S_{id}, r_i, \vec{x}_i)@T \longrightarrow \text{Time}@T, R(s, r_i + R)@T$$

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configurations denoting protocol sessions for which the timeout has passed are critical;
- ▶ **Denied CS:** $\langle \{R(s, r_{min}^s)@T_1, Av(s)@T_2\}, \{T_1 \leq T_2\} \rangle$
configurations are critical if a service is considered available at a time its resources have been exhausted:

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configurations are critical if a service is considered available at a time its resources have been exhausted:
- ▶ **Available CS:**
 $\langle \{R(s, r_{min}^s + R + 1)@T_1, Den(s)@T_2\}, \{T_1 \leq T_2\} \rangle$
service should not be considered denied at anytime when sufficient resources are available.

We extend our model to take into account **countermeasures**.

Countermeasures based on timeouts,

e.g., ReqTimeOut for mitigating the Slowloris attack.

- ▶ Trigger a timeout whenever a condition on the traffic is satisfied:

$$Time@T, R(s, R)@T_1, S_i(s, S_{id}, r_i, \vec{x}_i)@T_2, \text{TimeCM}(s, S_{id})@T \\ \longrightarrow Time@T, R(s, r_i + R)@T$$

Critical configuration: $\langle \{Time@T, \text{TimeCM}(s, S_{id})@T_1\}, \{T_1 < T\} \rangle$

- ▶ The connection S_{id} of service s is closed;
- ▶ The service's resources r_i are made available.

Experimental Results

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- ▶ We implemented the framework using Rewriting Modulo SMT in Maude.
- ▶ It uses symbolic search with the following symbols:
 - ▶ **Time Symbols**, that is, instead of instantiating time variable, we use time symbols that are constrained by a set of constraints. We use an SMT solver to check for the satisfiability of this set.
 - ▶ **Intruder and Service Resource Symbols:** Instead of using concrete values for intruder and service resources, we use intruder resource symbols and service resource symbols;
 - ▶ **Protocol Instance Symbols:** Instead of creating one protocol session, we allow the intruder to create several instances of a protocol session representing a burst from the intruder.

Experimental Results

We carried out bounding model checking with the following bounds:

- ▶ **Bound on the Number of Parallel Symbolic Protocols (pxs).**
- ▶ **Bound on the Number of Messages at a Time (pxs).**

	No Bounding		Bounded msgs_1		Bounded pxs		Bounded msgs_1 and pxs	
Attack	States	Time (s)	States	Time (s)	States	Time (s)	States	Time (s)
SL [1]	18	0.4	16	0.4	8	0.1	7	0.1
SL [2]	409	13	277	11.2	27	0.4	17	0.4
SL [3]	–	–	–	–	228	4.7	56	2.6
STCAM [2]	17	0.3	15	0.3	16	0.3	14	0.2
STCAM [3]	387	12.5	266	9.7	361	10.3	243	9.2
STCAM [4]	–	–	–	–	12783	561	6322	474

- ▶ We refine the notion of a DoS attack taking into account the duration of the attack.
- ▶ We propose a framework for analyzing the security of systems against DoS attacks:
 - reasoning about service's resources;
 - reasoning about intruder's resources;
 - reasoning about service timeouts;
- ▶ We obtain complexity results for the DoS problem and a general non-critical reachability problem for real time MSR;
- ▶ We automate the verification using Rewriting Modulo SMT.

- ▶ Capture a larger class of security problems that are closely related to DoS attacks.
- ▶ Use statistical model checking to investigate effectiveness of intruder strategies and attack defenses.
- ▶ Investigate how different resource-bounded intruder models can be compared.

Thank you!

Showing that a trace of a dense time MSR is non-critical involves not only the configurations it contains, but also an infinite number of configurations obtained by decomposing *Tick* rules in order to faithfully capture the continuity of time.

Definition (Non-Critical Traces)

Let \mathcal{R} be a set of timed MSR rules and \mathcal{CS} a critical configuration specification. A trace \mathcal{P} of \mathcal{R} rules is **non-critical** if it contains no critical configuration and if no critical configuration is reachable along any trace obtained by matching any subtrace of \mathcal{P} on the left below with the one on the right:

$$\mathcal{S}_i \xrightarrow{\text{Tick}_\varepsilon} \mathcal{S}_{i+1} \qquad \mathcal{S}_i \xrightarrow{\text{Tick}_{\varepsilon_1}} \mathcal{S}' \xrightarrow{\text{Tick}_{\varepsilon_2}} \mathcal{S}_{i+1}$$

where ε_1 and ε_2 are arbitrary non-negative real numbers, such that, $\varepsilon = \varepsilon_1 + \varepsilon_2$ holds.