

Beyond Labels: Permissiveness for Dynamic Information Flow Enforcement

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An observation

The designer of a

- dynamic,
- flow-sensitive,
- permissive, and
- sound

information flow mechanism
is forced to think about:



This paper

- Enforcement mechanisms for label chains.
 - **Block** executions that are deemed unsafe.
 - **No leak** through enforcement actions (label chains deduction, blocking).
 - **Strong threat model**: *observation* produced on updates to variables and labels during normally terminated and blocked executions.
- Theorems that relate length of label chains to **permissiveness**.

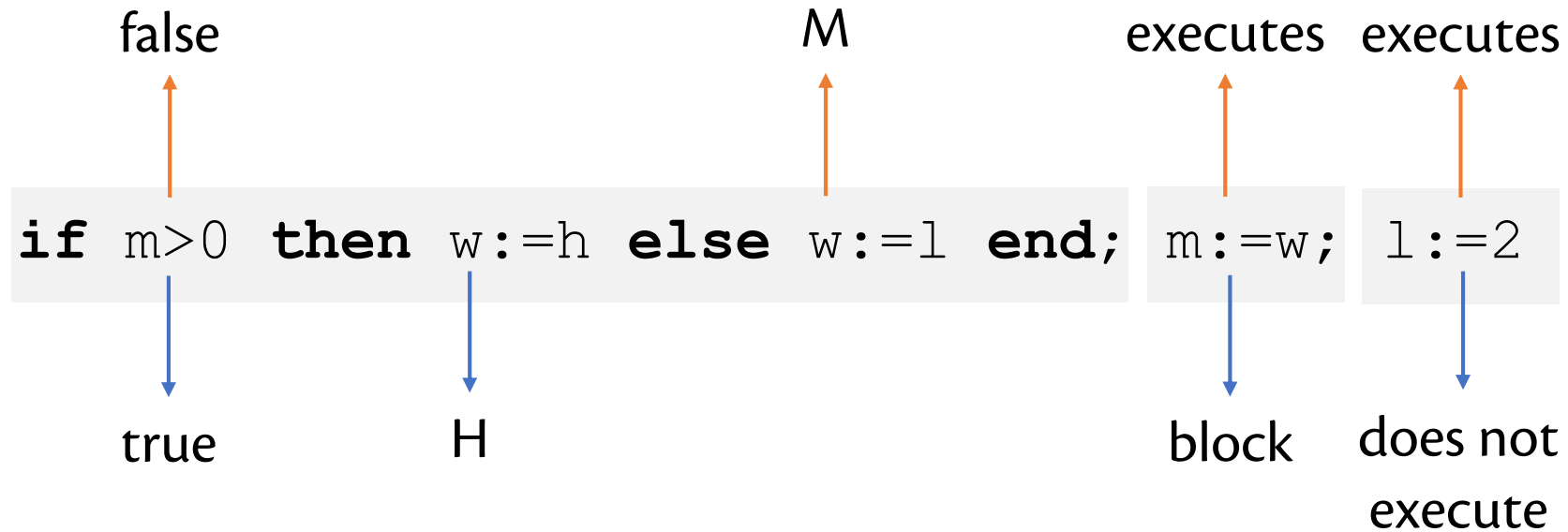
More observations
on variables and
labels in chains \Rightarrow Increased
permissiveness

Example

```
if m>0 then w:=h else w:=l end; m:=w; l:=2
```

- Lattice of labels: $L \sqsubset M \sqsubset H$
- Constants are tagged with L.
- *Anchor* variable l is tagged with *fixed* L; m with M; h with H.
- *Flexible* variable w is tagged with a *flow-sensitive* label.

A dynamic analysis

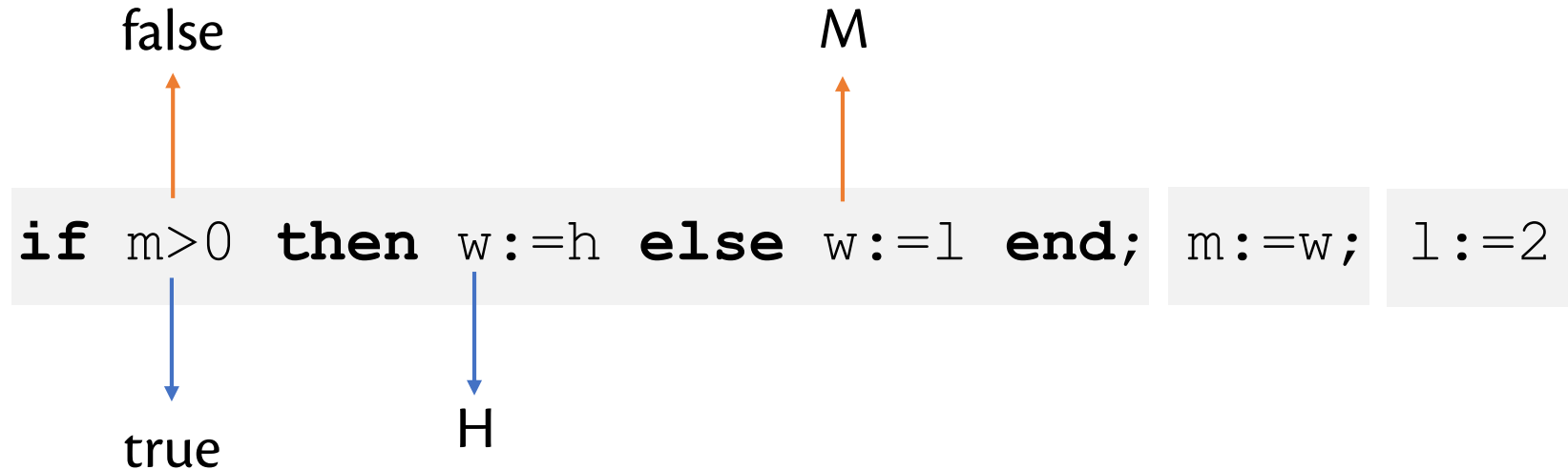


`m` leaks to:

- Principals reading variable `l`.
- Principals reading the flow-sensitive label of `w`.

Strong Threat Model

Metalabels represent sensitivity of labels



But, what is the sensitivity of the metalabel of `w`?

Label chains

- A variable x is associated with label chain

$$\langle \ell_1, \ell_2, \dots, \ell_i, \dots \rangle$$

\downarrow \downarrow \downarrow

$$T(x) \quad T^2(x) \quad T^i(x)$$

$T^{i+1}(x)$ is the sensitivity of $T^i(x)$.

- Flexible variable: the entire label chain is updated at every assignment
- Anchor variable: $T(x)$ is fixed
$$\langle \ell_1, \perp, \dots, \perp, \dots \rangle$$
- Monotonically decreasing: $\ell_1 \supseteq \ell_2 \supseteq \dots \supseteq \ell_i \supseteq \dots$

Why monotonically decreasing label chains?

Consider, instead, a non-monotonically decreasing label chain for x :

$\langle L, H, \dots \rangle$

- Principals assigned label L are authorized to read the value in x .
- When read access to x succeeds, these principals conclude that $T(x) = L$.
- So, principals assigned L learn the value of $T(x)$, even though the sensitivity of $T(x)$ is H .

Enforcer ∞ -Enf: assignment to flexible variable

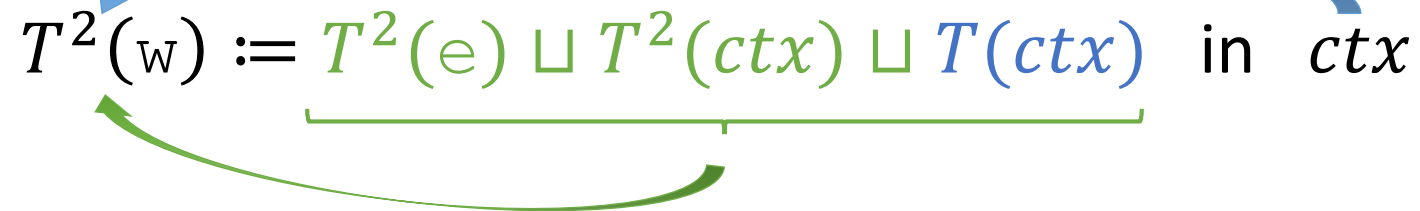
$w := e$ in ctx



$T(w) := \underbrace{T(e) \sqcup T(ctx)}_{\text{green}} \text{ in } ctx$



$T^2(w) := \underbrace{T^2(e) \sqcup T^2(ctx) \sqcup T(ctx)}_{\text{green}} \text{ in } ctx$



$T^i(w) := T^i(e) \sqcup T^i(ctx) \sqcup \dots \sqcup T^2(ctx) \sqcup T(ctx) \text{ in } ctx$

ctx of C is set $\{b, b'\}$:

if b **then**

if b' **then**

C

Enforcer ∞ -Enf: assignment to flexible variable

$$\forall i: T^i(w) := T^i(e) \sqcup T^i(ctx) \sqcup \dots \sqcup T^2(ctx) \sqcup T(ctx)$$

But, due to monotonically decreasing label chains, simplifies to:

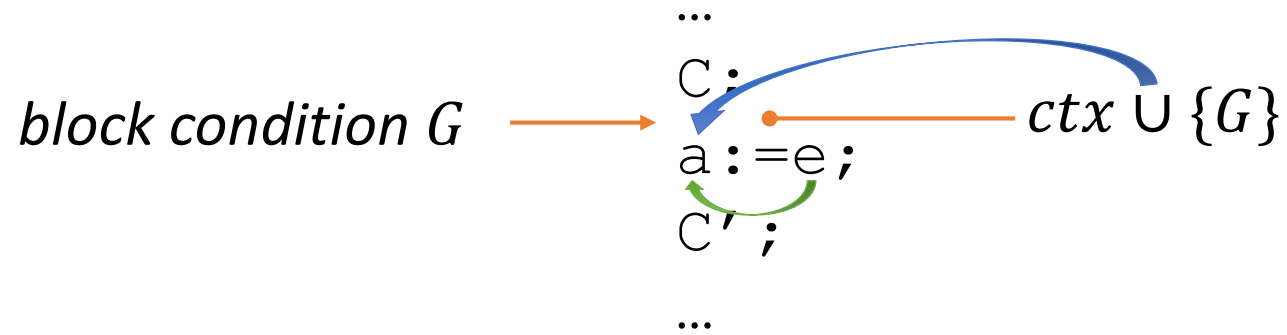
$$\forall i: T^i(w) := T^i(e) \sqcup T(ctx)$$

Enforcer ∞ -Enf: assignment to anchor variable

block condition G \longrightarrow

```
...  
C;  
a := e;  $\xrightarrow{\text{ctx}}$   
C';  
...
```

Enforcer ∞ -Enf: assignment to anchor variable



$$G \Rightarrow (T(e) \sqcup T(ctx) \sqcup T(G) \sqsubseteq T(a))$$

Given monotonically decreasing label chains, a solution for G is :

- $T(e) \sqcup T(ctx) \sqsubseteq T(a)$

Enforcer ∞ -Enf: assignment to anchor variable

...
C;
Block Unless $T(e) \sqcup T(ctx) \sqsubseteq T(a)$
a := e;
C';
...

$ctx \cup \{G\}$ —

It prevents leaks though blocking.

Given monotonically decreasing label chains, a solution for G is :

- $T(e) \sqcup T(ctx) \sqsubseteq T(a)$

∞ -Enf satisfies Block-safe Noninterference (BNI)

No leak through variables, label chains, and blocking.

Observations

Enforcer

Lattice

Command

k -BNI(E, L, C)

$\forall \ell \in L: \forall M, M':$

$$M|_{\ell} = M'|_{\ell}$$

$\wedge \tau = \text{trace}_E(C, M)$ is finite

$\wedge \tau' = \text{trace}_E(C, M')$ is finite

$$\Rightarrow \tau|_{\ell}^k =_{obs} \tau'|_{\ell}^k$$

Termination Insensitive NonInterference

$\tau = \text{trace}_E(C, M)$ terminates normally
 $\tau' = \text{trace}_E(C, M')$ terminates normally

Termination Sensitive NonInterference

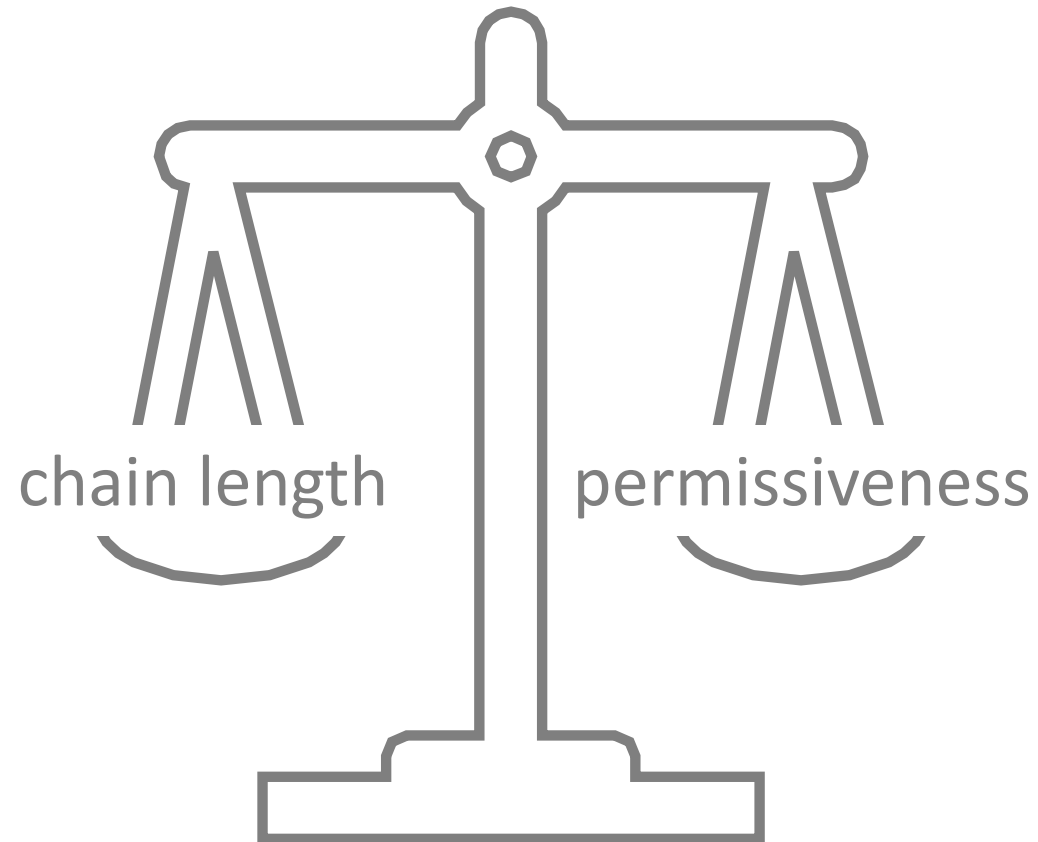
$\tau = \text{trace}_E(C, M)$
 $\tau' = \text{trace}_E(C, M')$

Enforcer k -Enf

For $k \geq 2$:

- k -Enf is based on ∞ -Enf to compute the first k labels of chains.
- k -Enf conservatively approximates the sensitivity of $T^k(x)$ to be itself:
 - $T^{k+1}(x) = T^k(x)$.
- k -Enf generates observations for the first k labels.
- [Thm] k -Enf satisfies BNI.
- k -Enf conservatively approximates
 - $\langle \ell_1, \ell_2, \dots, \ell_k, \ell_{k+1}, \dots \rangle$ with
 - $\langle \ell_1, \ell_2, \dots, \ell_k, \ell_k \rangle$.

What is it lost when shorter chains approximate longer chains?



Permissiveness

- An enforcer E is *at least as permissive as* an enforcer E' , iff
 - Traces of E are at least as long as E' , and
 - E produces at most as restrictive label chains as E' .
- So, E generates at least as many observations on variables and labels as E' .

Permissiveness is lost when shorter chains approximate longer chains

- Assume enforcers E and E' satisfy BNI.
- E produces label chain Ω for flexible variable w at a particular program point.
- E' produces label chain Ω' for w at that program point.

Loss of permissiveness \downarrow

$$\begin{array}{l} \Omega: \langle \ell_1, \ell_2, \dots, \ell_i, \ell_{i+1}, \dots, \ell_k \rangle \\ \Omega': \langle \ell_1, \ell_2, \dots, \ell_i, \ell_i, \dots, \ell_i \rangle \end{array}$$

k -precise with $\ell_i \supseteq \ell_{i+1}$

i -dependent

Does such an Ω arise?

$\Omega: \langle \ell_1, \ell_2, \dots, \ell_i, \ell_{i+1}, \dots, \ell_k \rangle$ *k-precise with*
 $\ell_i \supseteq \ell_{i+1}$

- **Arbitrary initialization.**
 - Ω can be associated with flexible variable w at initialization.
- **Common initialization.**
 - All flexible variables are initially associated with $\langle \perp, \perp, \dots, \perp \rangle$.
 - [Thm] We have designed an enforcer that can associate Ω with w during execution of a command.
 - Optimization of k -Enf.

So, Ω can arise!

- Assume enforcers E and E' satisfy BNI.
- E produces label chain Ω for flexible variable w at a particular program point.
- E' produces label chain Ω' for w at that program point.

	$\Omega:$	$\langle \ell_1, \ell_2, \dots, \ell_i, \ell_{i+1}, \dots, \ell_k \rangle$	<i>k-precise</i> with $\ell_i \supseteq \ell_{i+1}$
		\sqcap \sqcap	
Loss of permissiveness	$\Omega':$	$\langle \ell_1, \ell_2, \dots, \ell_i, \ell_i, \dots, \ell_i \rangle$	<i>i-dependent</i>

[Thm] E' cannot be as permissive as E.

Changing threat model

- Strong threat model:
 - Principals observe updates to variables and labels in chains.
- Weakened threat model:
 - Principals **only** observe updates to variables.

How does the relation between
permissiveness and label chain length
change?

Weakened threat model

- [Thm] Enforcers that use label chains of length one are not at least as permissive as 2-Enf for lattice $\langle \{L, M, H\}, \sqsubseteq \rangle$.
 - With 2-Enf, the second label in a label chain enables the decision to block assignments to be more permissive.
- Open question: Are label chains with more than two elements useful under the weakened threat model?

Two-level lattice

- For the weakened threat model, one label is enough:
 - [Thm] Permissiveness is not lost comparing to 2-Enf.



From 30,000 feet...

- To increase permissiveness, we add metadata.
- But metadata might encode sensitive information.
- To prevent leaks without harming permissiveness, add more metadata.
- But storage is finite.
- So, there are storage VS permissiveness trade-offs.

Summary: longer label chains provide increased permissiveness

		Chain length > 1	Chain length > 2
Strong	Arbitrary Initialization	✓	✓
	Common Initialization	✓	✓
Weakened (common initialization)	3-level lattice	✓	?
	2-level lattice	✗	✗