## On the strongly generic undecidability of the halting problem

Alexander N. Rybalov Omsk State University rybalov@omskreg.ru

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### The halting problem (HP)

- Input: A Turing machine M
- Output:

YES if M halts on  $\delta(M)$ 

NO if M does not halt on  $\delta(M)$ 

here  $\delta$  is some effective coding of Turing machines by binary strings

**Question 1** Is there an algorithm deciding HP?

**Theorem 1 (Classics)** *HP is algorithmically undecidable.* 

#### Generic-case version of the HP

• Input: "Almost every" Turing machine M

• Output:

YES if M halts on  $\delta(M)$ 

NO if M does not halt on  $\delta(M)$ 

**Question 2** Is there an algorithm deciding HP for "almost all" inputs?

**Question 3** What does it mean "almost all"?

## Asymptotic density of sets of programs

- P is the set of all Turing machines
- $P_n$  is the set of all *n*-state machines
- *B* is some set of Turing machines
- **Definition 1** Asymptotic density of *B* is  $\mu(B) = \overline{\lim_{n \to \infty}} \frac{|B \cap P_n|}{|P_n|}.$

# The number of all *n*-state programs

Working alphabet is  $\Sigma = \{0, 1, \Box\}$ . Machine can move the head to left and to right cell of the tape. Every *n*-state program contains 3nrules of type

$$(q_i, a) \rightarrow (q_j, b, s),$$

for every state  $q_i$ , i = 1, ..., n and every symbol  $a \in \Sigma$ . Here  $a, b \in \Sigma$ ,  $s \in \{L, R\}$  and  $q_j$  may be final state.

This follows that the number of all *n*-state programs is

$$|P_n| = (6(n+1))^{3n}.$$

#### Generic sets of programs

**Definition 2** A set B of programs is called

- generic if  $\mu(B) = 1$
- negligible if  $\mu(B) = 0$
- strongly negligible if there are constants  $0 < \sigma < 1$  and C > 0 such that for every n

$$\frac{|B \cap P_n|}{|P_n|} < C\sigma^n,$$

i.e. the sequence of the proportion of all n-state programs in B exponentially fast converges to 0

• strongly generic if  $P \setminus B$  is strongly negligible

# Generic-case decidability and complexity of HP

**Question 4** Is there a generic set of Turing machines on which the HP is decidable?

**Theorem 2 (Hamkins, Miasnikov)** There is a generic set of Turing machines B such that HP is polynomial time decidable on B.

**Question 5** What about strongly generic sets on which HP is decidable?

**Theorem 3 (Main result)** There is no strongly generic set of Turing machines on which HP is decidable.

## How do we prove undecidability of classical HP?

Suppose HP is decidable, then

$$halt(x) = \begin{cases} 1, & \text{if } x = \delta(M) \text{ and } M(x) \downarrow, \\ 0, & \text{if } x = \delta(M) \text{ and } M(x) \uparrow. \end{cases}$$

is computable function on  $\delta(P)$ . Then the "diagonal" function

 $diag(x) = \begin{cases} \text{not def, if } x = \delta(M) \text{ and } M(x) \downarrow, \\ 0, & \text{if } x = \delta(M) \text{ and } M(x) \uparrow. \end{cases}$ is computable on  $\delta(P)$  too. But the machine M computing diag makes an error on  $\delta(M)$ :

if 
$$M(\delta(M)) \downarrow \Rightarrow diag(\delta(M)) = 0 \Rightarrow M(\delta(M)) \uparrow$$
.

if  $M(\delta(M)) \uparrow \Rightarrow diag(\delta(M))$  is not defined  $\Rightarrow M(\delta(M)) \downarrow$ .

## How to prove undecidability of HP on any strongly generic set?

Let S be a strongly generic set of programs. Suppose HP is decidable on S, then

$$halt(x) = \begin{cases} 1, & \text{if } x = \delta(M) \text{ and } M(x) \downarrow, \\ 0, & \text{if } x = \delta(M) \text{ and } M(x) \uparrow. \end{cases}$$

is computable function on  $\delta(S)$ . Hence the function

$$diag(x) = \begin{cases} \text{not def, if } x = \delta(M) \text{ and } M(x) \downarrow, \\ 0, & \text{if } x = \delta(M) \text{ and } M(x) \uparrow. \end{cases}$$
  
is computable on  $\delta(S)$  and computed by some machine  $M$ . To get a contradiction we must give  $M$  the input  $\delta(M)$ .

**Question 6** Should  $\delta(M)$  belong to  $\delta(S)$ ? Should *M* be in *S*?

**Lemma 1** For any computable function f the set C(f) of all machines computing f is not strongly negligible.

**Idea of proof.** M has k states and computes f.  $M^*$  has n > k states and program with the same transition rules as in M for first k states and arbitrary rules for n - k other states:

fixed 3k rules 
$$\begin{cases} (q_1, 0) \to \dots, \\ \dots \\ (q_k, \Box) \to \dots, \end{cases}$$

arbitrary  $\Im(n-k)$  rules  $\begin{cases} (q_{k+1},0) \to \dots, \\ \dots \\ (q_n,\Box) \to \dots \end{cases}$ 

 $M^*$  computes f. A is the set of all such  $M^*$ .

$$\frac{|C(f) \cap P_n|}{|P_n|} \ge \frac{|A \cap P_n|}{|P_n|} =$$
$$= \frac{(6(n+1))^{3(n-k)}}{(6(n+1))^{3n}} = \frac{1}{(6(n+1))^{3k}}.$$
So  $C(f)$  is not strongly negligible.

### Returning to HP.

- C(diag) is not strongly negligible
- $P \setminus S$  is strongly negligible.

 $\Rightarrow$  there is a machine M computing diag such that  $M \in S$ . That is all that we need to end proof of main theorem.

### The end. Thank you.